Towards the definition of learning systems with configurable operators and heuristics

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Introduction

- Machine learning techniques dealing with structured data:
 - Distances or kernel methods can be applied to any kind of data (similarity functions).
 - Inductive programming (ILP, IFP or IFLP) are able to tackle any kind of data (first-order logic, term rewriting systems).

Introduction

- The performance of these systems is linked to:
 - a transformation of the feature space to a more convenient, flat, representation, which typically leads to incomprehensible patterns in terms of the transformed (hyper-)space
 - use the original problem representation but rely on specialised systems with embedded operators
- It is very difficult to have general systems which are able to deal with different kinds of complex data.

Introduction

- We present a general rule-based learning setting where operators can be defined and customised for each kind of problem.
 - The generalisation operator to use depends on the structure of the data.
 - Adaptive and flexible rethinking of heuristics, with a model-based reinforcement learning approach.

Setting

- Machine learning operators are the tools to explore the hypothesis search space.
 - Some operators are usually associated to some heuristic strategies (e.g., generalisation operators and bottom-up strategies).
- Operators can be modified and finetuned for each problem:
 - Different to the use of feature transformations or specific background knowledge.
- This is a challenging proposal not sufficiently explored in machine learning.

Principles

Setting

- Operators can be written or modified by the user
 - We need a language for defining operators which can integrate the representation of:
 - **■** Examples.
 - Patterns.
 - Operators.

Setting

We have chosen a powerful popular programming language, Erlang:

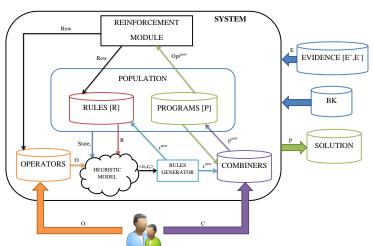


- A functional programming language, with reflection and higher-order primitives.
- Operators can be properly linked with the data structures used in the examples and background knowledge, so making the specification of new operators easier.
- The language also sets the general representation of examples as equations, patterns as rules and models as sets of rules.

Setting

General Architecture

General Architecture



Rule and Program Repositories

- Two internal repositories containing rules and programs.
- Initially, the set of rules *R* is populated with the positive evidence *E*⁺ and the set of programs *P* is populated defining unitary programs from the rules of *R*.
- Both repositories are updated at each step of the algorithm:
 - 1 The Rule Generator builds new rules (r^{new}) and they are added to R.
 - 2 By applying the combiners, (r^{new}) is mixed with the programs in P generating a new program p^{new} , and it is added to P.

System Operators

- The user can define his/her own set of operators, especially suited for the data structures of the problem: Adaptive system.
- An operator is defined as a function which is applied to a rule in order to generate new rules:
 - Given a rule $f(X) \rightarrow Y$ where the input attribute X is a list, the operator can extract the head of X and return it as the rhs of the new rule.
 - The operator could be defined as:

$$takeHead(f(X) o Y)$$
 [when X is a $List$] $o (f(X) o head(X))$

System Combiners

- Combiners evolve the population of programs.
 - Addition: adds the program that results from joining the new rule r^{new} generated by the Rule Generator with the best program (in terms of optimality);
 - **Union**: joins the two best programs (also in terms of optimality) in *P*.

Reinforcement Module

- A reinforcement learning module guides the *Rule Generator* in each step of the algorithm.
 - $lue{S}$ represents the system state as the set composed by R and P.
 - An action A is a tuple $\langle r_i, o_i \rangle$ where r_i is a rule and o_i is an operator.
- Given an state *S*, an action *A* is chosen by the *Heuristic Model* and sent to the *Rule Generator*. This creates new rules (and programs), which causes the system to move to a new state.

Reinforcement Module

- Initially, the Heuristic Model does not have enough evidence and the choice is random, but after a few iterations, the model is learnt by using a machine learning technique.
- This model is trained to predict the reward after a given action *A*, and with it we choose the action which maximises the estimated reward.
- Rewards:
 - From the optimality Opt^{new} of the new program p^{new}, the Reinforcement Module calculates a reward Rew.
 - Rew is used to update the optimality of the action $A = \langle r_i, o_i \rangle$.

Sequence Processing

- Learning a transformation over the words formed by a given alphabet.
 - Alphabet $\Sigma = \{a, t, c, g, u\}$
 - Transformation just replaces t with u.

Instance

$$\textit{trans}([t,c,g,a,t]) \rightarrow [\textit{u},c,g,a,\textit{u}]$$

Sequence Processing

Background Knowledge

$$f_{at}(a) \rightarrow t; \ f_{cg}(c) \rightarrow g; \dots$$
 (1)

Operators

$$applyMap(trans(X) o Y) \ \Rightarrow \ trans(X) o map(V_F, X)$$
 (2)

$$addBK_f(trans(X) o map(V_F, X)) \ \Rightarrow \ trans(X) o map(f, X)$$

$$genPat(trans(X) \rightarrow Y) \Rightarrow trans(V_S) \rightarrow Y$$
 (3)

Sequence Processing

- There is a simple sequence of operator applications which turns a simple example into a general solution.
- Given the instance $trans([t, c, g, a, t]) \rightarrow [u, c, g, a, u]$:

Solution Sequence Processing problem

```
\begin{split} \textit{genPat}(\textit{trans}([t,c,g,a,t]) \rightarrow [u,c,g,a,u]) & \Rightarrow & \textit{trans}(V_S) \rightarrow [u,c,g,a,u] \\ & \textit{applyMap}(\textit{trans}(V_S) \rightarrow [u,c,g,a,u]) & \Rightarrow & \textit{trans}(V_S) \rightarrow \textit{map}(V_F,V_S) \\ & \textit{addBK}_{\textit{f}_{tu}}(\textit{trans}(V_S) \rightarrow \textit{map}(V_F,V_S)) & \Rightarrow & \textit{trans}(V_S) \rightarrow \textit{map}(\textit{f}_{tu},V_S) \end{split}
```

Bunches of Keys

- Consider the well-known problem of determining whether a key in a bunch of keys can open a door.
- Each instance is given by a bunch of keys, where each key has several features: two-level structure (sets of lists).

Instance

```
opens([[abloy, 3, medium, narrow], [chubb, 6, medium, normal]]) = \top
```

Bunches of Keys

Background Knowledge

Operators

$$addBK(opens(X) = \top) \Rightarrow opens(X) \rightarrow setExists([], X)$$
 (5)

$$KCond_{cond_i}(opens(X) \rightarrow setExists(C, X)) \Rightarrow$$
 (6)
 $opens(X) \rightarrow setExists([cond_i|C], X)$

$$genPat(opens(X) = Y) \Rightarrow opens(V_L) \rightarrow Y$$
 (7)

(4)

Bunches of Keys

• If the prototype and operators are provided, given the original evidence for this example (five ⊤ instances and four ⊥ instances), it will return the following definition:

Solution Key of Bunches problem

$$opens(X) \rightarrow setExists([abloy, medium], X)$$

A bunch of keys opens the door if and only if it contains an abloy key of medium length.

- Web classification problem: web pages are assigned to pre-defined categories mainly according to their content (content mining).
- The evidence of the problem is modelled with 3 parameters described as follows:
 - Structure: the graph of links between pages is represented as ordered pairs where each node encodes a linked page
 - Content: the content of the web page is represented as a set of attributes with the keywords, the title, etc.
 - Use: the information derived from connections to a web server which is encoded by means of a numerical attribute with the daily number of connections.

- The goal of the problem is to categorise which web pages are about sports.
- A training example may look like this:

Instance

```
sportsWeb(Structure, Content, Connections) \rightarrow \top
```

where:

- $\begin{tabular}{ll} \hline & Structure = \\ & [\{[olympics, games], [swim]\}, \{[swim], [win]\}, \{[win], [medal]\}] \\ \hline \end{tabular}$
- $\quad \textbf{\textit{Content}} = [\{\textit{olympics}, 30\}, \{\textit{held}, 10\}, \{\textit{summer}, 40\}]$
- \blacksquare Connections = 20

Background Knowledge

$$graphExists(Edge, Graph)$$
 (8)

$$setExists(Key, List)$$
 (9)

Operators

$$addBK_{graph}(sportsWeb(S, C, U) \rightarrow \top) \Rightarrow$$
 (10)
 $sportsWeb(S, C, U) \rightarrow graphExists(\{[], []\}, S)$

$$\begin{aligned} & \textit{linkl}_{\textit{cond}_i}(\textit{sportsWeb}(S, C, U) \rightarrow \textit{graphExists}(\{X, Y\}, S)) \ \Rightarrow \\ & \textit{sportsWeb}(S, C, U) \rightarrow \textit{graphExists}(\{[\textit{cond}_i|X], Y\}, S) \end{aligned} \tag{11}$$

Operators

$$\begin{aligned} \textit{linkr}_{\textit{cond}_i}(\textit{sportsWeb}(S, C, U) \rightarrow \textit{graphExists}(\{X, Y\}, S)) & \Rightarrow \\ \textit{sportsWeb}(S, C, U) \rightarrow \textit{graphExists}(\{X, [\textit{cond}_i | Y]\}, S) \end{aligned} \tag{12}$$

$$genPat_1(sportsWeb(S, C, U) \to \top) \Rightarrow$$
 $sportsWeb(V_S, C, U) \to \top$ (13)

There are also some other operators to generalise the second and third arguments.

Our system found the following program which defines the sportsWeb function:

Solution Key of Bunches problem

```
 \begin{cases} sportsWeb(V_S, V_C, V_U) & \rightarrow & graphExists(\{[final], [match]\}, V_S). \\ sportsWeb(V_S, V_C, V_U) & \rightarrow & setExists([\{athens]\}, V_C). \\ sportsWeb(V_S, V_C, V_U) & \rightarrow & setExists([\{europe]\}, V_C). \end{cases}
```

If the word 'athens' or 'europe' appears in Content, and Structure contains the link {[final], [match]} then this is a sport web page. Conclusions and Future Work

Conclusions

Conclusions

- More general systems can be constructed by a flexible operator redefinition and the reuse of heuristics across problems and systems.
- In order to reduce the search space we rely on the definition of customised operators, depending on the data structures and problem at hand.
- We need a language for expressing operators for defining new operators easily.

Conclusions and Future Work

Conclusions

Conclusions

- The use of different operators precludes the system to use specialised heuristics for each of them.
- We have proposed this as a decision process, where operators are actions to be taken, and this is also seen as a reinforcement learning problem.

Conclusions and Future Work

Future Work

Future Work

- Transforming the prototype into a learning system, including all the issues in the architecture.
- We need to further develop and refine the heuristics module of the system:
 - Improved description of the state
 - Better reinforcement learning models (which could eliminate many useless explorations of the search space).